

Recap: Norms

What's a norm?

$$f: \mathbb{R}^n \rightarrow \mathbb{R}_0^+$$

$$\|\vec{x}\|$$

Define *norm*.

A function $\|\cdot\|: \mathbb{R}^n \rightarrow \mathbb{R}_0^+$

1. $\|\vec{x}\| > 0 \Leftrightarrow \vec{x} \neq \vec{0}$ ($\vec{x} \in \mathbb{R}^n$)

2. $\|\gamma \vec{x}\| = |\gamma| \|\vec{x}\|$ ($\vec{x} \in \mathbb{R}^n, \gamma \in \mathbb{R}$)

3. Δ -ineq. $\|\vec{x} + \vec{y}\| \leq \|\vec{x}\| + \|\vec{y}\|$



Norms: Examples

Examples of norms?

Euclidean norm
($p=2$)

p -norms

$$\left\| \begin{pmatrix} x_1 \\ \vdots \\ x_n \end{pmatrix} \right\|_p = \sqrt[p]{|x_1|^p + \dots + |x_n|^p}$$

($p \geq 1$) or $p = \infty$

Demo: Vector Norms [cleared]

Norms: Which one?

Does the choice of norm really matter much?

In finite dimensions, all vector norms
are equiv.

$\|\cdot\|, \|\cdot\|^*$ norms $\Rightarrow \exists \alpha, \beta > 0$

$$\alpha \|x\| \leq \|x\|^* \leq \beta \|x\| \quad (x \in \mathbb{R}^n)$$

Norms and Errors

If we're computing a vector result, the error is a vector.
That's not a very useful answer to 'how big is the error'.
What can we do?

true value: x_0^0
computed value: x^{12}

abs. error: $\|x_0^0 - x^{12}\| \leftarrow$

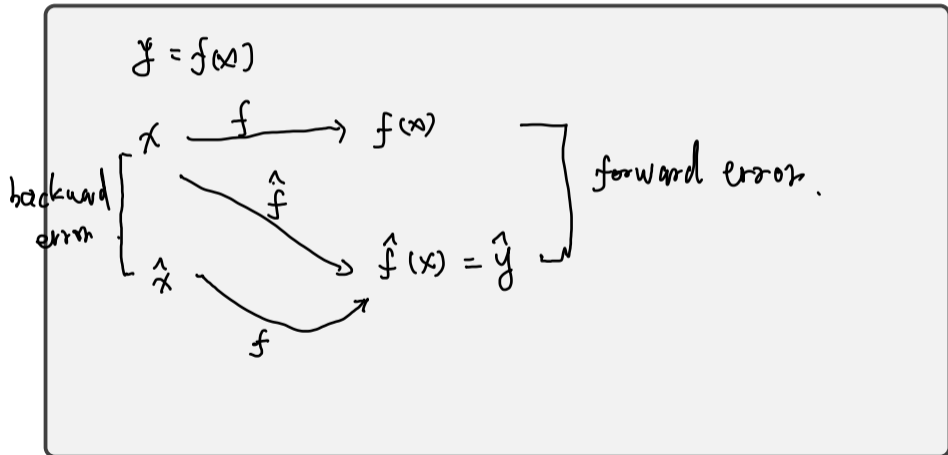
NO: ~~$\|x_0^0\| - \|x^{12}\|$~~

WRONG!
BAD!

Forward/Backward Error

Suppose *want* to compute $y = f(x)$, but *approximate* $\hat{y} = \hat{f}(x)$.

What are the forward error and the backward error?



Forward/Backward Error: Example

Suppose you wanted $y = \sqrt{2}$ and got $\hat{y} = 1.4$.
What's the (magnitude of) the forward error?

$$\begin{aligned}\sqrt{2} &\approx 1.41421 \\ \|\Delta y\| &= |1.4 - 1.41421\dots| \approx 0.01421 \\ \frac{|\Delta y|}{|y|} &\approx 1\%\end{aligned}$$

Forward/Backward Error: Example

Suppose you wanted $y = \sqrt{2}$ and got $\hat{y} = 1.4$.
What's the (magnitude of) the backward error?

$$\hat{x} = 1.4^2 = 1.96$$

$$\left| \frac{\Delta x}{x} \right| = \left| \frac{0.04}{2} \right| = 2\%$$

Forward/Backward Error: Observations

What do you observe about the relative magnitude of the relative errors?

want the ratio of $\frac{\text{forward error}}{\text{backward error}}$ to be
small.

Sensitivity and Conditioning

What can we say about amplification of error?

k κ

$$\Rightarrow |\text{rel. fwd error}| \leq \kappa \cdot |\text{rel. backw. error}|$$

\uparrow rel. condition number

$$\kappa = \max_x \frac{|\Delta y|/y}{|\Delta x|/x} \leftarrow \text{fa.}$$

\uparrow "Klappen"

\leftarrow bw.

If cond. nr. is small: "well-cond. problem"
large: "ill-conditioned"

$$\underline{3.14159} \rightsquigarrow 3.14$$

Example: Condition Number of Evaluating a Function

$$k = \max_x \frac{|\Delta y|/|y|}{|\Delta x|/|x|}$$

$y = f(x)$. Assume f differentiable.

Forward error: $\Delta y = f(x + \Delta x) - f(x) \approx f'(x) \cdot \Delta x$

Demo: Conditioning of Evaluating tan [cleared]

$$k \geq \frac{|\Delta y|/|y|}{|\Delta x|/|x|} = \frac{|f'(x)| \cdot \cancel{|\Delta x|} / |f(x)|}{\cancel{|\Delta x|} / |x|} = \frac{|f'(x) \cdot x|}{|f(x)|}$$

Stability and Accuracy

Previously: Considered *problems* or *questions*.

Next: Considered *methods*, i.e. computational approaches to find solutions.

When is a method *accurate*?

$$\| f(x) - \hat{f}(x) \| \text{ small}$$

When is a method *stable*?

- $\hat{x} = f^{-1}(\hat{f}(x))$ is close to x .
- stronger than "small condition number"