

## Truncation Error in Interpolation

If  $f$  is  $n$  times continuously differentiable on a closed interval  $I$  and  $p_{n-1}(x)$  is a polynomial of degree at most  $n$  that interpolates  $f$  at  $n$  distinct points  $\{x_i\}$  ( $i = 1, \dots, n$ ) in that interval, then for each  $x$  in the interval there exists  $\xi$  in that interval such that

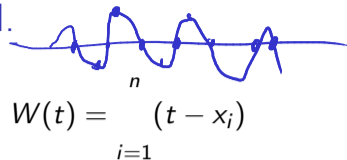
$$\underbrace{f(x) - p_{n-1}(x)}_{\text{Error}} = \frac{f^{(n)}(\xi)}{n!} \underbrace{(x - x_1)(x - x_2) \cdots (x - x_n)}_{w(x)}$$

$$R(x) = f(x) - p_{n-1}(x)$$

$$Y_x(t) = R(t) - \frac{R(x)}{w(x)} w(t)$$

$$(x \notin \{x_1, \dots, x_n\})$$

# Truncation Error in Interpolation: cont'd.



$$Y_x(t) = R(t) - \frac{R(x)}{W(x)} W(t) \quad \text{where} \quad W(t) = \prod_{i=1}^n (t - x_i)$$

- $Y_x(t)$  has  $n+1$  roots.  $\left\{ \begin{array}{l} \{x_1, \dots, x_n\} \text{ because } R(x_i) \neq 0 \\ W(x_i) = 0 \\ Y_x(x_i) = 0 \end{array} \right.$
- Rolle's theorem says  $Y_x'$  has at least  $n$  roots (btw. the  $x_i$ )
- $Y_x^{(n)}$  has at least one root:  $\xi$

$$Y^{(n)}(t) = f^{(n)}(t) - \frac{R(x)}{W(x)} n!$$

$$f^{(n)}(\xi) \cdot \frac{W(x)}{n!} = R(x)$$

$$R(t) = f - P_{n-1}$$

## Error Result: Connection to Chebyshev

What is the connection between the error result and Chebyshev interpolation?

$$f(x) - p_{n-1}(x) = \frac{f^{(n)}(\xi)}{n!} \prod_{i=1}^n (x-x_i)$$
$$\max_x |f(x) - p_{n-1}(x)| \leq \underbrace{\max_x \left| \frac{f^{(n)}(x)}{n!} \right|}_{\text{yellow wavy underline}} \cdot \underbrace{\max_x \left| \prod_{i=1}^n (x-x_i) \right|}_{\text{red underline}}$$
$$\min_{\{x_i\}} \max_x \left| \prod_{i=1}^n (x-x_i) \right| \Rightarrow \text{Chebyshev nodes!}$$

$\#$  = chebyshev approximating polynomial =  $p^*$

$$\|f(x) - p_{n-1}(x)\| \leq (1 + \Lambda_{n-1}) \|f(x) - p^*\|$$

Demo: Chebyshev Interpolation [cleared] (Part V)

## Error Result: Simplified From

Boil the error result down to a simpler form.

$$\begin{cases} |f^{(n)}(x)| \leq M, & x \in [x_1, x_n] \\ h = x_n - x_1 \end{cases}$$

$$E(h) := \max_x |f(x) - P_{n-1}(x)| \leq C \cdot M \cdot h^n$$

$$\Rightarrow E(h) = O(h^n), \quad h \rightarrow 0$$

$n$ -th order convergence.

[Demo: Interpolation Error \[cleared\]](#) [Demo: Jump with Chebyshev Nodes \[cleared\]](#)

## Going piecewise: Simplest Case

Construct a piecewise linear interpolant at four points.

$x_0, y_0$

$$f_1 = a_1x + b_1$$

2 unk.

$$f_1(x_0) = y_0$$

$$f_1(x_1) = y_1$$

2 eqn.

$x_1, y_1$

$$f_2 = a_2x + b_2$$

2 unk.

$$f_2(x_1) = y_1$$

$$f_2(x_2) = y_2$$

2 eqn.

$x_2, y_2$

$$f_3 = a_3x + b_3$$

2 unk.

$$f_3(x_2) = y_2$$

$$f_3(x_3) = y_3$$

2 eqn.

$x_3, y_3$

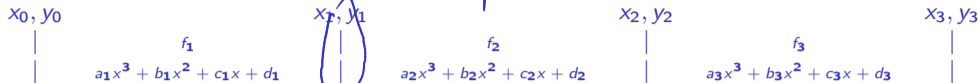
Why three intervals?

- 2 at end

- in the middle (add more as needed)

# Piecewise Cubic ('Splines')

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4 unk	4 unk	4 unk	
$f_1(x_0) = y_0$	$f_2(x_1) = y_1$	$f_3(x_2) = y_2$	} 6
$f_1(x_1) = y_1$	$f_2(x_2) = y_2$	$f_3(x_3) = y_3$	
	$f_1'(x_1) = f_2'(x_1)$	$f_2'(x_2) = f_3'(x_2)$	} 4
	$f_1''(x_1) = f_2''(x_1)$	$f_2''(x_2) = f_3''(x_2)$	
$f_1''(x_0) = 0$			$f_3''(x_3) = 0$

"natural spline"

# Piecewise Cubic ('Splines'): Accounting

$x_0, y_0$		$x_1, y_1$		$x_2, y_2$		$x_3, y_3$
	$f_1$		$f_2$		$f_3$	
	$a_1x^3 + b_1x^2 + c_1x + d_1$		$a_2x^3 + b_2x^2 + c_2x + d_2$		$a_3x^3 + b_3x^2 + c_3x + d_3$	



# Outline

Introduction to Scientific Computing

Systems of Linear Equations

Linear Least Squares

Eigenvalue Problems

Nonlinear Equations

Optimization

Interpolation

## **Numerical Integration and Differentiation**

Numerical Integration

Quadrature Methods

Accuracy and Stability

Gaussian Quadrature

Composite Quadrature

Numerical Differentiation

Richardson Extrapolation

Initial Value Problems for ODEs

Boundary Value Problems for ODEs

Partial Differential Equations and Sparse Linear Algebra

Fast Fourier Transform

Additional Topics



## Numerical Integration: About the Problem

What is numerical integration? (Or quadrature?)

$$I(f) = \int_a^b f(x) dx$$

What about existence and uniqueness?

- Riemann / Lebesgue.
- "f is piecewise continuous & bounded"

## Conditioning

Derive the (absolute) condition number for numerical integration.

