

- Example 2

- HW 8

Solving Nonlinear Equations

What is the goal here?

$$f(\vec{x}) = \vec{0}$$

↳ 1D case: $f(x) = 0$

Showing Existence

How can we show existence of a root?

- Intermediate value theorem; f continuous;



- Inverse function theorem: J_f^x invertible at some point $x \in \mathbb{R}^n$
Want: $f^{-1}(0) = \text{goal}$ \Rightarrow there exists $\varepsilon > 0$ so that f is invertible on $B(x, \varepsilon)$

- Contraction mapping theorem

$$g(x) = f(x) + x$$

A function $g: \mathbb{R}^n \rightarrow \mathbb{R}^n$ is called contractive if there exists $0 < \rho < 1$ so that $\|g(x) - g(y)\| \leq \rho \|x - y\|$.

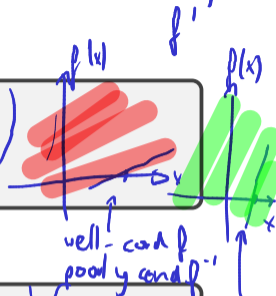
On a closed set $S \subseteq \mathbb{R}^n$ with $g(S) \subseteq S$ then exists a fixed point $x^* : g(x^*) = x^*$.

Sensitivity and Multiplicity

abs cond of evaluating f_1

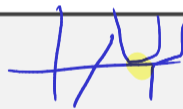
What is the sensitivity/conditioning of root finding?

$$\text{abs cond (root finding)} = \text{abs cond} (f^{-1}(\vec{0}))$$



What are multiple roots?

Example: $f(x) = (x - x_k)^2 \cdot \bar{p}(x)$



Def: $f(x^*) = 0, f'(x^*) = 0, \dots$
multiplicity 2

How do multiple roots interact with conditioning?

inverse is steep, therefore condition is poor.

Rates of Convergence

What is *linear convergence*? *quadratic convergence*?

$$\vec{e}_n = \vec{u}_n - \vec{u}$$

\vec{u}_k : guess at k 'th iteration

An iterative method converges with rate r iff

\vec{u} : true answer

\vec{e}_k : error

$$\lim_{k \rightarrow \infty} \frac{\|\vec{e}_{k+1}\|}{\|\vec{e}_k\|^r} = C \quad \begin{matrix} > 0 \\ < \infty \end{matrix}$$

$r=1$: linear conv

$r=2$: quadratic

$r>1$: superlinear

Previous carbon def: $\|\vec{e}_{k+1}\| \leq C \cdot \|\vec{e}_k\|^r$

$$\begin{aligned} \|\vec{e}_{k+1}\| &\leq C \cdot \|\vec{e}_k\| \\ \|\vec{e}_{k+1}\| &\leq C \cdot \|\vec{e}_k\|^2 \end{aligned}$$

About Convergence Rates

Demo: Rates of Convergence [cleared]

Characterize linear, quadratic convergence in terms of the 'number of accurate digits'.

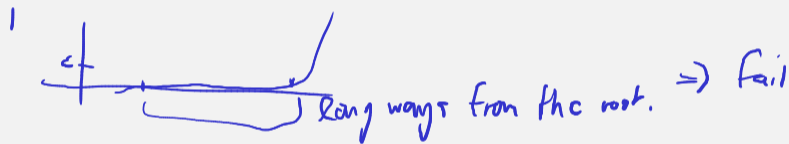
Linear: gains fixed number of digits
per it.

Quadratic: doubles number of digits.

Stopping Criteria

Comment on the 'foolproof-ness' of these stopping criteria:

1. $|f(x)| < \varepsilon$ ('residual is small')
2. $\|\mathbf{x}_{k+1} - \mathbf{x}_k\| < \varepsilon$
3. $\|\mathbf{x}_{k+1} - \mathbf{x}_k\| / \|\mathbf{x}_k\| < \varepsilon$

1.  \Rightarrow fail

2. Method gets stuck \Rightarrow fail



: rel accuracy
of roots with different
magnitudes not the
same:

3. Goes bad if $\|\vec{x}_k\|$ is small

Bisection Method

Demo: Bisection Method [cleared]

What's the rate of convergence? What's the constant?

linear

Fixed Point Iteration

$$\begin{aligned}x_0 &= \langle \text{starting guess} \rangle \\x_{k+1} &= g(x_k)\end{aligned}$$

Demo: Fixed point iteration [cleared]

When does fixed point iteration converge? Assume g is smooth.

Let x^* be the fixed pt. with $g(x^*) = x^*$
If $|g'(x^*)| < 1$, then there exists a neighborhood
where we have convergence.
$$e_{k+1} = x_{k+1} - x^* = g(x_k) - g(x^*)$$

Fixed Point Iteration: Convergence cont'd.

Error in FPI: $e_{k+1} = x_{k+1} - x^* = g(x_k) - g(x^*)$

$$e_{k+1} = g(x_k) - g(x^*) = g'(\theta_k)(x_k - x^*) = g'(\theta_k) e_k$$



$$\theta_k \in [x_k, x^*]$$

if close enough to x^* that

$$|g'(\theta_k)| < 1$$

\Rightarrow conv.

What if $g'(x^*) = 0$?

Does not imply that $g'(\theta_k) = 0$.



$$|g'(x^* + h)| \approx C|h|$$

$$|h| \approx |e_k|$$

$$\Rightarrow \|e_{k+1}\| \approx C \cdot h \cdot \|e_k\| \approx C \cdot \|e_k\|^2$$

Newton's Method

Derive Newton's method.

$$f(x) = 0?!$$

$$f(x_n + h) \approx f(x_n) + f'(x_n)h + \cancel{O(h^2)}$$

Solve $f(x_n) + f'(x_n)h = 0$ for h .

Use $x_{n+1} = x_n + h$.

$$x_{n+1} = x_n - \frac{f(x_n)}{f'(x_n)} = g(x_n)$$

Demo: Newton's method [cleared]

Convergence and Properties of Newton

What's the rate of convergence of Newton's method?

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Drawbacks of Newton?

[Demo: Convergence of Newton's Method](#) [cleared]