

- Quiz 2

CS 430

- HW1

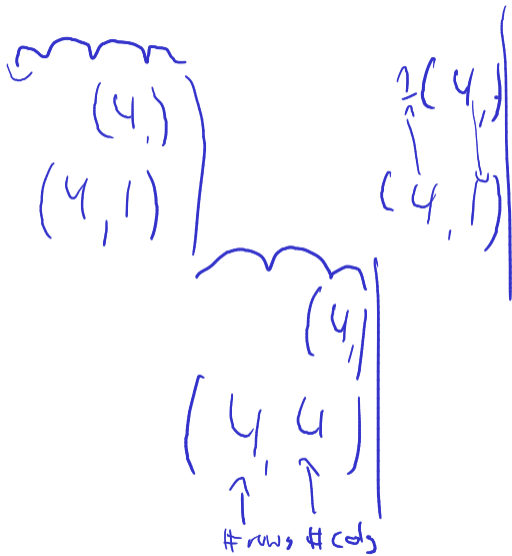
- Sign into forum at least once to create account

- Categorize forum posts

$$\begin{pmatrix} 1 & 2 & 3 & 4 \\ 11 & 12 & 13 & 14 \end{pmatrix} \approx 10$$



$$f'(x) \approx \frac{f(x+h) - f(x)}{h}$$



# Goals:

- numpy broadcast
- norms
- "errors"
  - ↳ Fw error / bw error / conditioning
- numbers

## Norms: Examples

Examples of norms?

$$\text{rel. error} = \frac{|x - \hat{x}|}{|x|}$$

(number / scalar)

$$\text{rel. error} = \frac{\|x - \hat{x}\|}{\|x\|}$$

(vector)

$$\left\| \begin{pmatrix} x_1 \\ \vdots \\ x_n \end{pmatrix} \right\|_p = \sqrt[p]{\sum_{i=1}^n |x_i|^p}$$

$\infty$ -norm takes max absolute value

$p$ -norms

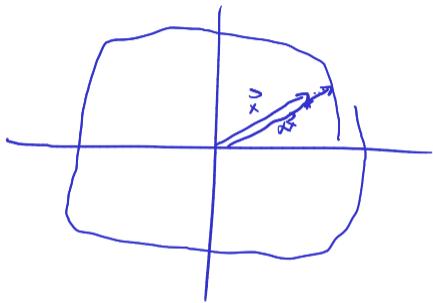
$p \geq 1$   
 $p = \infty$  } ok

Demo: Vector Norms [cleared]

Unit ball of  $\|\cdot\|$ :

$$\left\| \frac{x}{\|x\|} \right\| = \frac{1}{\|x\|} \cdot \|x\| = 1$$


$$\{ \vec{x} : \|\vec{x}\| = 1 \}$$

 $\alpha x_u$ 

$$\|\alpha x_u\| = 1$$

$$\frac{\|x_u\|}{\alpha} = 1$$

## Norms: Which one?


$$\| \begin{pmatrix} -1 \\ 1 \end{pmatrix} \|_1 = \sqrt{|-1| + |1|} = 2$$

Does the choice of norm really matter much?

$$\|x\|_2 \in \begin{matrix} \supset \\ \cup \\ \supset \end{matrix} \begin{matrix} \|x\|_1 \\ \|x\|_\infty \end{matrix}$$

In finite-d, all norms are equivalent.

$$\|\cdot\|, \|\cdot\|^*$$

$$\exists \alpha, \beta \in \mathbb{R}^+$$

$$\forall x \in \mathbb{R}^d:$$

$$\alpha \|x\| \leq \|x\|^* \leq \beta \|x\|$$

## Norms and Errors

If we're computing a vector result, the error is a vector.  
That's not a very useful answer to 'how big is the error'.  
What can we do?

$$\text{abs error} = \|\vec{x} - \vec{\hat{x}}\|$$

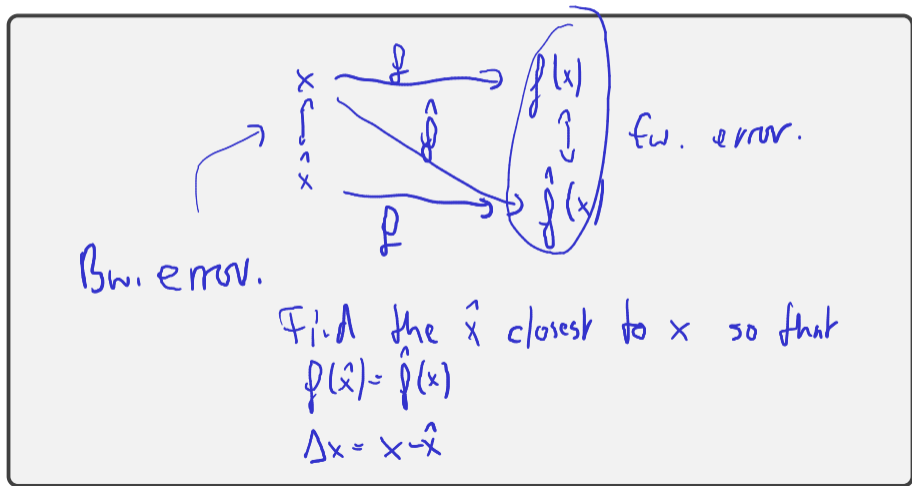
abs error  $\neq$

$$\|x\| - \|\hat{x}\|$$

## Forward/Backward Error <sup>out</sup> <sub>in</sub>

Suppose *want* to compute  $y = f(x)$ , but *approximate*  $\hat{y} = \hat{f}(x)$ .

What are the forward error and the backward error?





## Forward/Backward Error: Example



Suppose you wanted  $y = \sqrt{2}$  and got  $\hat{y} = 1.4$ .  
What's the (magnitude of) the forward error?

$$\text{Rel. fwd. error} \quad |\Delta y| = |1.4 - 1.41421| = 0.0142 \dots$$

$$\frac{|\Delta y|}{|y|} = \frac{0.01 \dots}{1.4141 \dots} \approx 0.01$$

## Forward/Backward Error: Example

Suppose you wanted  $y = \sqrt{2}$  and got  $\hat{y} = 1.4$ .  
What's the (magnitude of) the backward error?

$$\text{Find } \hat{x} \text{ s.t. } \sqrt{\hat{x}} = 1.4 \quad \hat{x} = 1.96$$

Backward error:

$$|\Delta x| = |1.96 - 2| = 0.04$$

Rel. bwd.

$$\frac{|\Delta x|}{|x|} \approx 0.02$$

## Forward/Backward Error: Observations

What do you observe about the relative magnitude of the relative errors?

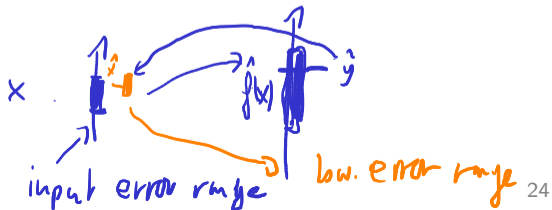


## Forward/Backward Error: Observations

What do you observe about the relative magnitude of the relative errors?

- ▶ In this case: Got smaller, i.e. variation damped out.
- ▶ Typically: Not that lucky: Input error amplified.
- ▶ If backward error is smaller than the input error: result “as good as possible”.

This amplification factor seems worth studying in more detail.



## Sensitivity and Conditioning

Consider a more general setting: An input  $x$  and its perturbation  $\hat{x}$ .

$$\frac{|f(x) - f(\hat{x})|}{|f(x)|} \leq \kappa_{\text{rel}} \frac{|x - \hat{x}|}{|x|}$$

forward/output error

input/inv. error.

If such a factor exists, it is called the (relative) condition number

$$\kappa_{\text{rel}} = \max_{(x, \hat{x}) \in S} \frac{|f(x) - f(\hat{x})|}{|f(x)|} \bigg/ \frac{|x - \hat{x}|}{|x|}$$

) sup

## Absolute Condition Number

Can you also define an *absolute* condition number?

