December 3, 2024 Announcements

- Exam & grades out - HW 10 tomorray

Goals

Review $S_{x}^{5}f(x) dt \approx S_{x}^{5}\rho_{xy}(x) = \sum_{i=1}^{5}f(x_{i}) \omega_{i}^{5}$ $f(x_{i}) = \rho_{h-i}(x_{i})$ grad, ruly $E(h) = O(h^{p})$ as h->0 "order of acch In - refinement

High-order polynomial interpolation requires a high degree of smoothness of the function.

Idea: Stitch together multiple lower-order quadrature rules to alleviate smoothness requirement.







Observation: Composite quadrature loses an order compared to non-composite.

Idea: If we can estimate errors on each subinterval, we can shrink (e.g. by splitting in half) only those contributing the most to the error. (adaptivity)

Taking Derivatives Numerically $e^{i\alpha} = \cos(i\beta r) \left(e^{i\alpha}\right) = i\alpha e^{i\alpha r}$ Why shouldn't you take derivatives numerically? [x]] e a x]]. (= || e^{iax} ||... · O imboulded operator ~ conditing · cancellation · amplifics arolic

Numerical Differentiation: How?

How can we take derivatives numerically?

$$\int [t_{x}] dx = p_{n-1}(x) = \int d_{x} d_{y} = \int d_{y} d_{y} d_{y} = \int d_{y} d_{y} = \int d_{y} d_{y} d_{y} d_{y} = \int d_{y} d_{y} d_{y} d_{y} d_{y} = \int d_{y} d_$$

Demo: Taking Derivatives with Vandermonde Matrices [cleared] (Basics)



Demo: Taking Derivatives with Vandermonde Matrices [cleared]

Differentiation Matrices

How can numerical differentiation be cast as a matrix-vector operation?

 $\sqrt{\vec{z}} = p_{n-1} \left(\vec{x} \right) = f(\vec{z}) \quad (=) \quad \vec{z} = \sqrt{-1} p(\vec{z})$ $\sqrt{\vec{z}} = p_{n-1} \left(\vec{x} \right) \approx p'(\vec{z}) \quad (=) \quad \sqrt{-1} \vec{z} \approx f'(\vec{z})$ $f'(\vec{x}) = \bigvee' \bigvee' \neg f(\vec{x})$

Demo: Taking Derivatives with Vandermonde Matrices [cleared] (Build D)





Properties of Differentiation Matrices

How do I find second derivatives?

Does *D* have a nullspace?

Demo: Taking Derivatives with Vandermonde Matrices [cleared] (Shifting and scaling the nodes)

Numerical Differentiation: Shift and Scale

Does D change if we shift the nodes $(x_i)_{i=1}^n \rightarrow (x_i + c)_{i=1}^n$?

Does D change if we scale the nodes $(x_i)_{i=1}^n \to (\alpha x_i)_{i=1}^n$?

Finite Difference Formulas from Diff. Matrices

How do the rows of a differentiation matrix relate to FD formulas?

Assume a large equispaced grid and 3 nodes w/same spacing. How to use?

Finite Differences: via Taylor

p' (x) = p(++h) - p(+) + o(h) (Plx4) + plx1+ p'(x1-L + p"(x1.h2 + ... J(15) (x) = ~ f(x117L) - - -

More Finite Difference Rules

Similarly:

$$f'(x) = \frac{f(x+h) - f(x-h)}{2h} + O(h^2)$$

(Centered differences)

Can also take higher order derivatives:

$$f''(x) = \frac{f(x+h) - 2f(x) + f(x-h)}{h^2} + O(h^2)$$

Can find these by trying to match Taylor terms.

Alternative: Use linear algebra with interpolate-then-differentiate to find FD formulas.

Demo: Finite Differences vs Noise [cleared] **Demo:** Floating point vs Finite Differences [cleared]

Richardson Extrapolation

Deriving high-order methods is hard work. Can I just do multiple low-order approximations (with different h and get a high-order one out?

Suppose we have $F = \tilde{F}(h) + O(h^p)$ and $\tilde{F}(h_1)$ and $\tilde{F}(h_2)$.