CS450-Recitation-2

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Content

- Recap of Linear Algebra
- 2 LU/Gaussian Elimination
- O Practice Questions (In the mean time)

$$2x - y = 1$$
$$x + y = 2$$

The intersection of the two lines gives the unique point (x, y) = (1, 1), which is the solution. However, if two lines are parallel, cases need to be discussed separately.

$$x\begin{bmatrix}2\\2\end{bmatrix}+y\begin{bmatrix}-1\\1\end{bmatrix}=\begin{bmatrix}1\\2\end{bmatrix}$$

Matrix form:

$$\begin{bmatrix} 2 & -1 \\ 2 & 1 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} 1 \\ 2 \end{bmatrix}$$

Thus, $\mathbf{A}\mathbf{x} = \mathbf{b}$. $\mathbf{x} = \begin{bmatrix} x \\ y \end{bmatrix}$, and $\mathbf{b} = \begin{bmatrix} 1 \\ 2 \end{bmatrix}$.
 $\mathbf{A} = \begin{bmatrix} \mathbf{a_1} & \mathbf{a_2} \end{bmatrix}$

 $Ax = xa_1 + ya_2$ Linear combination of columns.

System of Equations

$$AB = \begin{bmatrix} Ab_1 & Ab_2 \end{bmatrix}$$

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Consider $\mathbf{A}\mathbf{x} = \mathbf{b}$:

- Existence and uniqueness of solution depend on whether **A** is singular or nonsingular.
- Previous case, nonsingular if two lines intersect.
- In singular cases, infinite solutions if $\mathbf{b} \in span(\mathbf{A})$ else none.
- **A** is nonsingular iff \mathbf{A}^{-1} exits.
- **A** is nonsingular iff $det(\mathbf{A}) \neq 0$.
- Check Michael/Lecture notes for more equivalent definition of nonsingular

$$\mathbf{A} = egin{bmatrix} 1 & 1+\epsilon \ 1-\epsilon & 1 \end{bmatrix}$$

- What is the determinant of A?
- In floating-point arithmetic, for what range of values of ϵ will **A** be singular?
- In floating-point arithmetic, for what range of values of ϵ will the computed value of the determinant be zero?

Show that the matrix

$$\mathbf{A} = \begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \\ 7 & 8 & 9 \end{bmatrix}$$

is singular.

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$$\begin{bmatrix} 2 & -1 \\ 2 & 1 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} 1 \\ 2 \end{bmatrix}$$

Easy to solve if **A** is orthogonal, diagonal.

Easy to solve if **A** is upper triangular(backward-substitution) or lower triangular(Forward-substitution).

Within this linear system, it's easy to achieve triangularity.

$$\begin{bmatrix} 2 & -1 \\ 2 & 1 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} 1 \\ 2 \end{bmatrix}$$

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Within this linear system, it's easy to achieve.

$$\begin{bmatrix} 2 & -1 \\ 2 & 1 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} 1 \\ 2 \end{bmatrix}$$
$$\begin{bmatrix} 1 & 0 \\ -1 & 1 \end{bmatrix} \begin{bmatrix} 2 & -1 \\ 2 & 1 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ -1 & 1 \end{bmatrix} \begin{bmatrix} 1 \\ 2 \end{bmatrix}$$
$$\begin{bmatrix} 2 & -1 \\ 0 & 2 \end{bmatrix} \begin{bmatrix} x \\ y \end{bmatrix} = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

More details will be covered in the following lectures.

System of Equations

Linear Algebra Recap:

Given an $m \times n$ matrix **A**,

Definition 1

the rank of a matrix \mathbf{A} is defined as the dimension of the vector space generated (or spanned) by its columns. This corresponds to the maximal number of linearly independent columns of \mathbf{A} .

Definition 2

the null-sapce of a matrix **A** is defined as is the set of solutions to the equation Ax = 0. The dimension of the null space of **A** is called the nullity of **A**.

Rank Nullity theorem

Given an $m \times n$ matrix **A**, rank(**A**) + nullity(**A**) = n.

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$$\mathbf{A} = egin{bmatrix} 1 & 1+\epsilon \ 1-\epsilon & 1 \end{bmatrix}$$

- What is the LU factorization of A?
- In floating-point arithmetic, for what range of values of ϵ will the computed value of U be singular?

$$\mathbf{A} = \begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \\ 7 & 8 & 9 \end{bmatrix}$$

Find the unit vector spanning the null space of **A**.

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