

Power Iteration

$$A x = \lambda x \quad (x_i, \lambda_i)$$

What are the eigenvalues of A^{1000} ?

Assume $|\lambda_1| > |\lambda_2| > \dots > |\lambda_n|$ with eigenvectors x_1, \dots, x_n .

Further assume $\|x_i\| = 1$.

$$x_0 = \alpha x_1 + \beta x_2 + \gamma x_3 + \dots$$

$$x_{k+1} = A x_k$$

$$x_{k+1} = A^k x_0 = \alpha \lambda_1^k x_1 + \beta \lambda_2^k x_2 + \gamma \lambda_3^k x_3 + \dots$$

$$= \lambda_1^k \left(\alpha x_1 + \beta \underbrace{\left(\frac{\lambda_2}{\lambda_1}\right)^k}_{\ll 1} x_2 + \gamma \underbrace{\left(\frac{\lambda_3}{\lambda_1}\right)^k}_{\ll 1} x_3 + \dots \right)$$

$$k \rightarrow \infty \quad \frac{x_{k+1}}{\lambda_1^k} \rightarrow \alpha x_1$$

Converges to the eigenpair (x_1, λ_1)

Power Iteration: Issues?

What could go wrong with Power Iteration?

- overflow \rightarrow normalize

- x_0 without component along x_1

($\alpha=0$)

\rightarrow unlikely to happen if random start.

\rightarrow floating point operations usually introduce such component.

- $|\lambda_1| = |\lambda_2| \rightarrow$ does not converge to x_1 (method fails)

What about Eigenvalues?

Power Iteration generates eigenvectors. What if we would like to know eigenvalues?

$$\text{Rayleigh quotient: } \lambda = \frac{x^T A x}{x^T x}$$

where x is the converged eigenvector from power iteration

Convergence of Power Iteration

What can you say about the convergence of the power method?

Say $\mathbf{v}_1^{(k)}$ is the k th estimate of the eigenvector \mathbf{x}_1 , and

$$e_k = \|\mathbf{x}_1 - \mathbf{v}_1^{(k)}\|.$$

$$e_k \sim c \left| \frac{\lambda_2}{\lambda_1} \right|^k \Rightarrow \frac{\|e_{k+1}\|}{\|e_k\|} = \frac{\left(\frac{\lambda_2}{\lambda_1} \right)^{k+1}}{\left(\frac{\lambda_2}{\lambda_1} \right)^k} = \left| \frac{\lambda_2}{\lambda_1} \right| = \text{constant}$$

$$\|e_{k+1}\| = \left| \frac{\lambda_2}{\lambda_1} \right| \|e_k\|$$

linear convergence

Cost: $O(n^2)$ mat-vec

Matrix A with eigenvalues $|\lambda_1| > |\lambda_2| > \dots > |\lambda_n|$

Inverse Power Iteration:

$$Ax = \lambda x \implies A^{-1}Ax = A^{-1}\lambda x \implies \frac{1}{\lambda}x = A^{-1}x$$

$(\frac{1}{\lambda}, x)$ is eigenpair of A^{-1}

Power iteration $x_{k+1} = Ax_k \rightarrow$ converges to largest $\lambda \implies \lambda_1$

Inverse Power iteration $x_{k+1} = A^{-1}x_k \rightarrow$ converges to largest $(\frac{1}{\lambda}) \implies \lambda_n$

Algorithm: x_0 : random

for $k=0, 1, \dots$

solve $Ax_{k+1} = x_k$

normalize

Cost = ? $O(n^3)$

Factorize first

solve sequence
of triangular solve

Convergence:

$$\frac{\|e_{k+1}\|}{\|e_k\|} = \left| \frac{\lambda_n}{\lambda_{n-1}} \right|$$

Matrix A with eigenvalues $|\lambda_1| > |\lambda_2| > \dots > |\lambda_n|$ $Ax = \lambda x$

Shifted Inverse:

$$x_{k+1} = (A - \sigma I)^{-1} x_k \longrightarrow \text{converges to largest eigenvalue of } (A - \sigma I)^{-1}$$

$$(A - \sigma I)^{-1} x = \bar{\lambda} x \rightarrow \frac{1}{\bar{\lambda}} x = (A - \sigma I)x = Ax - \sigma Ix = \lambda x - \sigma x$$

$$\bar{\lambda} = \frac{1}{\lambda - \sigma}$$

largest $\bar{\lambda} \Rightarrow$ smallest $(\lambda - \sigma) \Rightarrow$ Find λ that is closest to σ

Algorithm:

$x_0 =$ random

for $k=0, 1, \dots$

 solve $(A - \sigma I)x_{k+1} = x_k$

 normalize

Factorize first $O(n^3)$ once
solve triangular systems $O(n^2)$ k times

Convergence:

$$\frac{\|x_{k+1}\|}{\|x_k\|} = \frac{|\lambda_{\text{closest}} - \sigma|}{|\lambda_{\text{second-closest}} - \sigma|}$$

Rayleigh Quotient iteration

$$\sigma_k = \frac{X_k^T A X_k}{X_k^T X_k}$$

$$(A - \sigma_k I) X_{k+1} = X_k$$

- at least quadratic convergence
 - needs to factorize every iteration (more expensive)
 - may not converge to desired eigenvector.
- } trade-off

GO TO DEMO!

Simultaneous Iteration

Power iteration methods \rightarrow one eigenvalue at a time

What if we need all of them?

What happens if we carry out power iteration on multiple vectors simultaneously?

- start random $x_0 \in \mathbb{R}^{n \times p}$ $p \leq n$

- iterate $X_{k+1} = AX_k$

- Issues:
 - overflow \rightarrow rescale
 - X increasingly ill-conditioned

(all columns of X converge to x_1)

(x_1, λ_1) : dominant eigen pair of A
 $|\lambda_1| > |\lambda_2| \dots$

Fix: Orthogonalize!

Orthogonal iteration

start $X_0 \in \mathbb{R}^{n \times p}$

$$A = QR \rightarrow \text{upper triangular}$$

orthogonal

Factorize : $X_0 = Q_0 R_0$

Update : $X_1 = A Q_0$

Factorize : $X_1 = Q_1 R_1 \longrightarrow X_1 = Q_1 R_1 = A Q_0 \Rightarrow A = Q_1 R_1 Q_0^T$

Update : $X_2 = A Q_1$

Factorize : $X_2 = Q_2 R_2 \longrightarrow X_2 = Q_2 R_2 = A Q_1 \Rightarrow A = Q_2 R_2 Q_1^T$

Update : $X_3 = A Q_2$

⋮

Factorize : $X_k = Q_k R_k \longrightarrow X_k = Q_k R_k = A Q_{k-1} \Rightarrow A = Q_k R_k Q_{k-1}^T$

Update : $X_{k+1} = A Q_k$

when $Q_k \approx Q_{k-1} \rightarrow$ converges (not a good convergence check!)

Algorithm

start $X_0 \in \mathbb{R}^{n \times p}$

for $k=0, 1, \dots$

Factorize $Q_k, R_k = \text{la-qr}(X_k)$

Update $X_{k+1} = A Q_k$

- slow convergent
- computationally expensive per iteration

At convergence : $A \approx Q_k R_k Q_k^T \rightarrow R_k$ diagonal entries are the eigenvalues of A

QR iteration

start $A_0 = A$

$$X_0 = I \rightarrow X_0 = Q_0 R_0 \Rightarrow R_0 = Q_0 = I \Rightarrow X_1 = AI$$

Factorize: $A_0 = Q_0 R_0 \longrightarrow Q_0^T Q_0 R_0 = Q_0^T A_0 \longrightarrow R_0 = Q_0^T A_0$

Update: $A_1 = R_0 Q_0 \longrightarrow A_1 = Q_0^T A_0 Q_0$

Factorize: $A_1 = Q_1 R_1 \longrightarrow Q_1^T Q_1 R_1 = Q_1^T A_1 \longrightarrow R_1 = Q_1^T A_1$

Update: $A_2 = R_1 Q_1 \longrightarrow A_2 = Q_1^T A_1 Q_1$

Factorize: $A_2 = Q_2 R_2 \longrightarrow Q_2^T Q_2 R_2 = Q_2^T A_2 \longrightarrow R_2 = Q_2^T A_2$

Update: $A_3 = R_2 Q_2 \longrightarrow A_3 = Q_2^T A_2 Q_2$

⋮

Factorize: $A_k = Q_k R_k \longrightarrow Q_k^T A_k = Q_k^T Q_k R_k \longrightarrow R_k = Q_k^T A_k$

Update: $A_{k+1} = R_k Q_k \longrightarrow A_{k+1} = Q_k^T A_k Q_k$

Algorithm:

start $X_0 = A$

for $k=0,1,\dots$

Factorize $Q_k, R_k = \text{la-gr}(X_k)$

Update $X_{k+1} = R_k Q_k$

$X_{k+1} \approx X_k \rightarrow \text{converges}$

X_k diagonal entries are the eigenvalues of A

QR + Shift

start $X_0 = A$

for $k=0,1,\dots$

Factorize $Q_k, R_k = \text{la-gr}(X_k - \sigma_k I)$

Update $X_{k+1} = R_k Q_k + \sigma_k I$

$X_{k+1} \approx X_k \rightarrow \text{converges}$

$$\rightarrow X_k - \sigma_k I = Q_k R_k \Rightarrow Q_k^T (X_k - \sigma_k I) = Q_k^T Q_k R_k = R_k$$

still a similarity transform: $X_{k+1} = R_k Q_k + \sigma_k I$

$$X_{k+1} = Q^T (X_k - \sigma_k I) Q_k + \sigma_k I$$

$$X_{k+1} = Q_k^T X_k Q_k - \sigma_k Q_k^T Q_k + \sigma_k I$$

\rightarrow Shift is chosen so that it is close to existing eigenvalue.