

Today

- ∇ VD

↳ Min mod

↳ SSP

↳ limitations/extensions

- FEM

Announcements

- Feedback form

- Lecture format?

Harten's Lemma

Theorem (Harten's Lemma)

If a scheme can be written as

$$\bar{u}_{j,\ell+1} = \bar{u}_{j,\ell} + \lambda(C_{j+1/2}\Delta_+\bar{u}_j - D_{j-1/2}\Delta_-\bar{u}_j)$$

with $C_{j+1/2} \geq 0$, $D_{j+1/2} \geq 0$, $1 - \lambda(C_{j+1/2} + D_{j+1/2}) \geq 0$ and $\lambda = \Delta t / \Delta x$, then it is TVD.

As a matter of notation, we have

$$\Delta_+ u_j = u_{j+1} - u_j,$$

$$\Delta_- u_j = u_j - u_{j-1}.$$

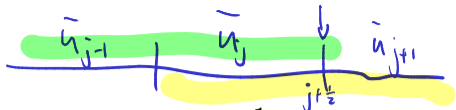
We have omitted the time subscript for the time level ℓ .

Minmod Scheme

Still assume $f'(u) \geq 0$.

$$f_{j+1/2}^{*,(1)} = f\left(\bar{u}_j + \underbrace{\frac{1}{2}(\bar{u}_{j+1} - \bar{u}_j)}_{\tilde{u}_j^{(1)}}\right),$$

$$f_{j+1/2}^{*,(2)} = f\left(\bar{u}_j + \underbrace{\frac{1}{2}(\bar{u}_j - \bar{u}_{j-1})}_{\tilde{u}_j^{(2)}}\right).$$



Design a 'safe' thing to use for \tilde{u} :



$$\text{minmod}(a, b) = \begin{cases} a & |a| \leq |b| \\ b & |b| < |a| \\ 0 & ab < 0 \end{cases} \quad ab \geq 0$$

$$\tilde{u}_j^{(3)} = \text{minmod}(\tilde{u}_j^{(1)}, \tilde{u}_j^{(2)})$$

$$f_{j+1/2}^{*,(3)} = f\left(\bar{u}_j + \tilde{u}_j^{(3)}\right)$$

Minmod is TVD

$$\bar{u}_{j,t+1} = \bar{u}_j + \lambda (C \Delta_+ - D \Delta_-)$$

Show that Minmod is TVD:

$$\begin{aligned}\bar{u}_{j,t+1} &= \bar{u}_j - \lambda (f(\bar{u}_j + \tilde{u}_j) - f(\bar{u}_{j-1} + \tilde{u}_{j-1})) \\ &= \bar{u}_j - \lambda (-D_{j-\frac{1}{2}} \Delta_- \bar{u}_j)\end{aligned}$$

$$D_{j-\frac{1}{2}} = \frac{f(\bar{u}_j + \tilde{u}_j) - f(\bar{u}_{j-1} + \tilde{u}_{j-1})}{\bar{u}_j - \bar{u}_{j-1}} = f'(\xi) \frac{\bar{u}_j - \bar{u}_{j-1} + \tilde{u}_j - \tilde{u}_{j-1}}{\bar{u}_j - \bar{u}_{j-1}}$$

$$\underbrace{= f'(\xi)}_{\geq 0} \left[1 + \frac{a_j}{\underbrace{\bar{u}_j - \bar{u}_{j-1}}_{0 \leq \epsilon \leq \frac{1}{2}}} - \frac{\tilde{u}_{j-1}}{\underbrace{\bar{u}_j - \bar{u}_{j-1}}_{0 \leq \epsilon \leq \frac{1}{2}}} \right] \geq 0$$

Minmod: CFL restriction?

Derive a time step restriction for Minmod.

$$D_{j-\frac{1}{2}} \leq f'(q) \cdot \frac{\Delta x}{\Delta t} \leq \max_{\dots} |f'(q)| \cdot \frac{\Delta x}{\Delta t}$$

$$0 \leq 1 - \lambda D_{j-\frac{1}{2}} \geq 1 - \frac{\lambda}{2} \max |f'| \Leftrightarrow \lambda \max |f'| \leq \frac{2}{\lambda}$$

What about Time Integration? $TV(u_{\ell+1})$

SSPRK(2,2)

$$u^{(1)} = u_{\ell} + h_t L(u_{\ell}), \quad u_{\ell+1} = \frac{u_{\ell}}{2} + \frac{1}{2}(u^{(1)} + h_t L(u^{(1)})).$$

Above: A version of RK2 with L the ODE RHS. Will this cause wrinkles?

$$\rightarrow TV(\alpha \vec{u} + (1-\alpha)\vec{v}) \leq \alpha TV(\vec{u}) + (1-\alpha)TV(\vec{v}) \quad (0 \leq \alpha \leq 1)$$

$$TV(u_{\ell+1}) = TV\left(\frac{u_{\ell}}{2} + \frac{1}{2}(u^{(1)} + h_t L(u^{(1)}))\right)$$

$$\leq \frac{1}{2} TV(u_{\ell}) + \frac{1}{2} TV(u^{(1)} + h_t L(u^{(1)}))$$

$$\leq \frac{1}{2} TV(u_{\ell}) + \frac{1}{2} TV(u_{\ell} + h_t L(u_{\ell}))$$

$$\leq \frac{1}{2} TV(u_{\ell}) + \frac{1}{2} TV(u_{\ell}) = TV(u_{\ell})$$

Total Variation is Convex

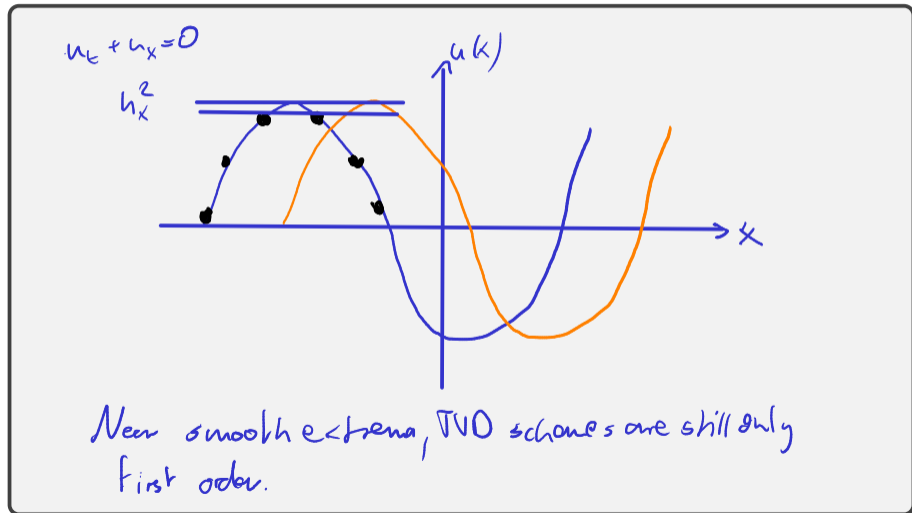
Show: $TV(\cdot)$ is a convex functional.

$$0 \leq \alpha \leq 1$$

$$\begin{aligned} & TV(\alpha \vec{u} + (1-\alpha) \vec{v}) \\ & \leq \sum_j \left| \alpha (u_j - u_{j-1}) + (1-\alpha) (v_j - v_{j-1}) \right| \\ & \leq \alpha \underbrace{\sum_j |u_j - u_{j-1}|}_{TV(u)} + (1-\alpha) \underbrace{\sum_j |v_j - v_{j-1}|}_{TV(v)} \end{aligned}$$

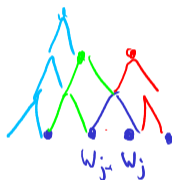
TVD and High Order

Can TVD schemes be high order everywhere?



High Order at Smooth Extrema

- ▶ TVB Schemes [Shu '87]
- ▶ ENO [Harten/Engquist/Osher/Chakravarthy '87]
 - ▶ Define $W_j = w(x_{j+1/2}) = \int_{x_{1/2}}^{x_{j+1/2}} u(\xi, t) d\xi = h_x \sum_{i=1}^j \bar{u}_i$
 - ▶ Observe $u_{j+1/2} = w'(x_{j+1/2})$.
 - ▶ Approximate by interpolation/numerical differentiation.
 - ▶ Start with the linear function $p^{(1)}$ through W_{j-1} and W_j
 - ▶ Compute divided differences on (W_{j-2}, W_{j-1}, W_j)
 - ▶ Compute divided differences on (W_{j-1}, W_j, W_{j+1})
 - ▶ Use the one with the smaller magnitude to extend $p^{(1)}$ to quadratic
 - ▶ (and so on, adding points on the side with the lowest magnitude)
- ▶ WENO [Liu/Osher/Chan '94]



Outline

Introduction

Finite Difference Methods for Time-Dependent Problems

Finite Volume Methods for Hyperbolic Conservation Laws

Theory of 1D Scalar Conservation Laws

Numerical Methods for Conservation Laws

Higher-Order Finite Volume

Outlook: Systems and Multiple Dimensions

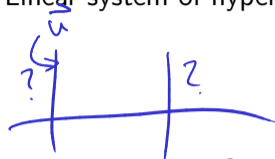
Finite Element Methods for Elliptic Problems

Discontinuous Galerkin Methods for Hypberbolic Problems

A Glimpse of Integral Equation Methods for Elliptic Problems

Systems of Conservation Laws

Linear system of hyperbolic conservation laws, $A \in \mathbb{R}^{m \times m}$:



Assumptions on A ?

$$\begin{aligned} \mathbf{u}_t + A\mathbf{u}_x &= 0, \\ \mathbf{u}(x, 0) &= \mathbf{u}_0(x). \end{aligned}$$

$$u_{tt} = u_{xx}$$

$$\begin{aligned} u_t &= v_x \\ v_t &= u_x \end{aligned}$$

$$\rightarrow u_{tt} = v_{xt} = v_{tx} = u_{xx}$$

Hyperbolic if A diagonalizable, real eigenvalues

$$A \vec{r}_p = \lambda_p \vec{r}_p \quad (p=1 \dots m)$$

Called strictly hyperbolic if λ_p are all distinct.

$$\vec{v} = R^{-1} \vec{u} \quad \rightarrow \quad \vec{v}_t + \Lambda \vec{v}_x = \vec{0}$$

"characteristic variables"

$$AR = R\Lambda$$

Linear System Solution

$$\mathbf{v} = R^{-1}\mathbf{u}, \quad \mathbf{v}_t + \Lambda \mathbf{v}_x = 0.$$

Write down the solution.

$$u(x, t) = \sum_p r_p v_p(x - \lambda_p t)$$

$$\vec{v}(x) = R^{-1} \vec{u}(x, 0)$$

What is the impact on boundary conditions? E.g. $(\lambda_p) = (-c, 0, c)$ for a BC at $x = 0$ for $[0, 1]$? ↑ v_3

Can only specify a BC on v_3 .

Characteristics for Systems (1/2)



Consider system $\mathbf{u}_t + f(\mathbf{u})_x = 0$. Write in quasilinear form

$$\mathbf{u}_t + A(\mathbf{u}) \mathbf{u}_x = 0 \quad A(\mathbf{u}) = f'(\mathbf{u})$$

When hyperbolic?

$A(\mathbf{u})$ diag. w/ real eigs.
strictly if eigs. are distinct. } only local

Characteristics for Systems (2/2)



What about characteristics/shock speeds?

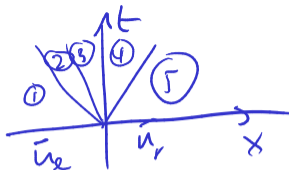
- Considering char. var.: "characteristic" still makes sense, in characteristics through (x, t)
- char speeds: not an ODE

Are values of u still constant along characteristics?

no, but CV are.

Shocks and Riemann Problems for Systems

$$\begin{aligned} \mathbf{u}_t + A\mathbf{u}_x &= 0, \\ \mathbf{u}(x, 0) &= \begin{cases} \mathbf{u}_l & x < 0, \\ \mathbf{u}_r & x > 0. \end{cases} \end{aligned}$$



Solution? (Assume strict hyperbolicity with $\lambda_1 < \lambda_2 < \dots < \lambda_m$.)