

① Jacobi's Iteration
 Initially
 ~~$x_0 = 0$~~

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Analysis

$x_0 = 0$

for $k = 1$ to k_{max}

$x_k = x_{k-1} + D^{-1}(b - Ax_{k-1})$

In practice

$x_0 = 0$

$x = x + D^{-1}(b - Ax)$

• Two main questions re. complexity:

(1) How much work per iteration?

(2) How many iterations?

- A nested loop!

$x = 0 \quad r = b$

for $k = 1$ to k_{max}

$\alpha = \|r\|_2 = \sqrt{r^T r}$

• If $\alpha < \epsilon$ tol break

$x = x + D^{-1}r$

$r = b - Ax$

$O((2d+1)n)$

end

$2n + \text{comm}$

$2n \quad (x_i = x_i + d_i^{-1} r_i)$

$x = 0 \quad r = b$

for $k = 1$ to k_{max}

$s = D^{-1}r$

$\alpha = \|s\|_2$

• If $\alpha < \epsilon$ tol break

$x = x + s$

$r = b - Ax = b - A(x_{k-1} + s)$

$= b - Ax_{k-1} - As = r - As$

end

n
 $2n$
 n
 $O((2d+1)n)$

$d=1$	$10n \cdot k$
2	$17n \cdot k$
3	$18n \cdot k$

$O((2d+1)n)$

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$$- [\underline{x}_{k+1} = \underline{x}_k + \underline{D}^{-1}(\underline{b} - A\underline{x}_k)]$$

$$+ [\underline{x} = \underline{x}_k + \underline{D}^{-1}(\underline{b} - A\underline{x})]$$

$$\underline{e}_{k+1} = \underline{e}_k - \underline{D}^{-1}A\underline{e}_k$$

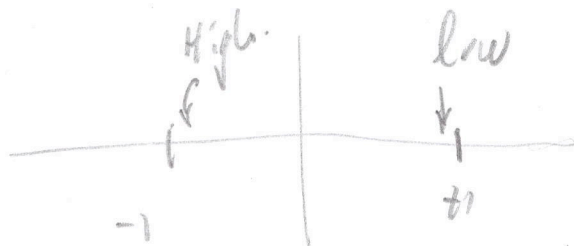
$$= (\underline{I} - \underline{D}^{-1}A)\underline{e}_k$$

$$= \underline{G}\underline{e}_k$$

Spectral radius of \underline{G} -

• Note - high wavenumber of $\underline{D}^{-1}A = \underline{G}$ is moved towards origin because of ^{-1}A .

$$\text{①) } \underline{D} = \frac{2b}{h^2} \underline{I}$$



③

Start with smallest eigenvalue of A_j

$$\lambda_{\min}(A_j) = d\pi^2 + O(h^2)$$

$$\lambda_{\max}(G) = \lambda(I - \tau^2 A) = 1 - \frac{h^2}{2} \cdot (d\pi^2 + O(h^2))$$

$$\sim 1 - \frac{(\pi h)^2}{2}$$

$$\lambda_{\min}(G) = 1 - \frac{h^2}{2} \lambda_{\max}(A)$$

$$\lambda_{\max}(A) = d \cdot \frac{2}{h^2} (1 - \cos \theta_n)$$

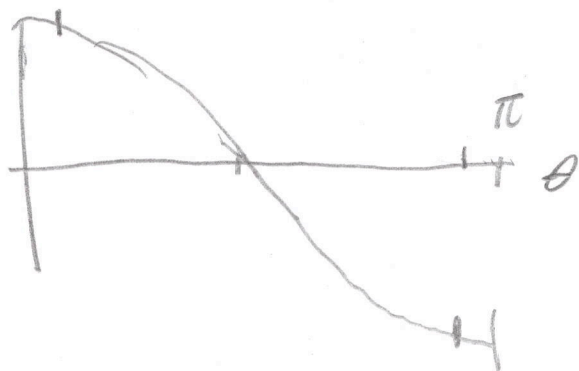
$$\theta_k = \frac{\pi k h}{L} = \frac{\pi k}{N} = \frac{\pi k}{n+1}$$

$$\theta_n = \frac{\pi n}{n+1}$$

$$\cos \theta_n = ?$$

$$= -1 \cdot \cos \theta_1$$

$$\cos \theta_1 = \cos \frac{\pi h}{L} = 1 - \frac{1}{2} \frac{\pi^2 h^2}{L^2} + \frac{1}{4!} \frac{\pi^4 h^4}{L^4} - \dots$$



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$$\therefore \lambda_{\max}(A) = \frac{dz}{h^2} (1 + \cos \theta_w)$$

$$= \frac{zd}{h^2} \left[z - \frac{\pi^2 h^2}{2} + o(h^4) \right]$$

$$\lambda_{\min}(G) = 1 - \frac{h^2}{2d} \left(\frac{zd}{h^2} \left(z - \frac{\pi^2 h^2}{2} + o(h^4) \right) \right)$$

$$= -1 + \frac{\pi^2 h^2}{2} + o(h^4)$$

$$|\lambda_{\min}(G)| = 1 - \frac{\pi^2 h^2}{2} + o(h^4) \sim |\lambda_{\max}(G)|$$

$$\rho(G) \sim 1 - \frac{\pi^2 h^2}{2} \quad (\sim 1 \text{ "})$$

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Vector Norms

Consider a vector norm: $\|\underline{x}\|_x$ - ($\underline{x} \in \mathbb{R}^n$)

Ex: $\|\underline{x}\|_1 = \sum_{j=1}^n |x_j|$

i $\|\underline{x}\|_\infty = \max_j |x_j|$

iii $\|\underline{x}\|_p = \left[\sum_{j=1}^n |x_j|^p \right]^{\frac{1}{p}}$

iv $\|\underline{x}\|_2 = \left[\sum_{j=1}^n |x_j|^2 \right]^{\frac{1}{2}} = \sqrt{\underline{x}^T \underline{x}}$

If A SPD, can also ~~write~~ define

v) $\|\underline{x}\|_A = (\underline{x}^T A \underline{x})^{\frac{1}{2}}$

For (iv) and (v), we also have an associated inner product

$$(\underline{u}, \underline{v}) := \underline{u}^T \underline{v} \quad \longrightarrow \quad \|\underline{v}\|_2 = (\underline{u}, \underline{u})^{\frac{1}{2}}$$

$$(\underline{u}, \underline{v})_A := \underline{u}^T A \underline{v} \quad \|\underline{v}\|_A = (\underline{u}^T, \underline{u})_A^{\frac{1}{2}}$$

⑥ equivalence of norms.

• For a fixed, every pair of vector norms satisfies ^{the following} an equivalence of norms property:

There exist constants c and C , dependent on n , but not on \underline{x} s.t.

$$c \|\underline{x}\|_0 \leq \|\underline{x}\|_p \leq C \|\underline{x}\|_0$$

• What this says is that, if $\|\underline{x}_k\|_0 \rightarrow 0$ then $\|\underline{x}_k\|_p \rightarrow 0$.

• That is, if we bound the error in one norm as $k \rightarrow \infty$, then it is bounded in all other vector norms (n -fixed!),

⑦

Matrix Norms

- We will work almost exclusively with induced matrix norms, defined as follows

$$\|A\|_2 = \max_{x \in \mathbb{R}^n} \frac{\|Ax\|_2}{\|x\|_2} = \max_{\substack{x \in \mathbb{R}^n \\ \|x\|_2 = 1}} \|Ax\|_2$$

- $\|A\|_2$ ~~measures~~ indicates the maximum possible "stretching" of any input vector x .
- Of course we can ~~not~~ have $\|A\|_2 < 1$.
- Moreover $\|A\|_2 = 0$ only for $A = 0$.

• IF $A = A^T$, $\|A\|_2 = \rho(A)$

• $\|A\|_\infty = \max_i \sum_{j=1}^n |a_{ij}|$ (max row sum)

• $\|A\|_1 = \max_j \sum_{i=1}^n |a_{ij}|$ (max col sum)

⑧

- Let's look at the stability of $\|A\|_x$.
- Return to our convergence rate question:

$$\underline{e}_{k+1} = G \underline{e}_k \quad , \quad \underline{e}_0 = \underline{x} - \underline{x}_0 = \underline{x}$$

$$\|e_{k+1}\|_x = \|G e_k\|_x$$

$$\leq \|G\|_x \|e_k\|_x \quad (\text{Def'n of } \|G\|_x)$$

$$\leq \|G\|_x^{k+1} \|e_0\|_x$$

$$= \|G\|_x^{k+1} \|\underline{x}\|$$

\therefore Relative error is bounded by

$$\boxed{\frac{\|e_k\|_x}{\|\underline{x}\|} \leq \|G\|_x^k}$$

Q

Note - For uniform grid case, $D(A) = a_{ii} \cdot I$

$$\begin{aligned} \therefore G &:= I - D^{-1}A = I - \frac{1}{a_{ii}}A \\ &= I^T - \frac{1}{a_{ii}}A^T = G^T \end{aligned}$$

$$\therefore \|G\|_2 = \rho(G)$$

So, for any \underline{x} and initial guess $\underline{x}_0 = 0$,

$$\frac{\|\underline{e}_k\|_2}{\|\underline{x}\|_2} \leq \rho(G)^k$$

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For our particular case

$$\rho(G) = 1 - \epsilon = 1 - \frac{\pi^2 h^2}{2} + \mathcal{O}(h^4)$$

Q: What k for
 $(1 - \epsilon)^k \leq \text{tol} := 10^{-6}$?

Note that $e^{-\epsilon} = 1 - \epsilon + \frac{\epsilon^2}{2} - \frac{\epsilon^3}{6} - \dots$

$$(1 - \epsilon)^k \approx (e^{-\epsilon})^k = e^{-k\epsilon} \approx 10^{-6} \approx e^{-12}$$

$$k \approx \frac{12}{\epsilon} = 12 \left(\frac{2}{\pi^2 h^2} \right) = \frac{24}{10} \cdot N^{-2} \approx 2.5 N^2$$

(11)

Amount of work / iter:

$$w = (10 + 4d) \cdot u = (10 + 4d) N^d \quad \begin{cases} 9 \\ 13 \\ 17 \end{cases}$$

Iterations $2.5 N^2$

$$w = wk = \begin{cases} 35 N^3 \\ N^4 \\ N^5 \end{cases}$$