

Today

- IE overview
- Loads of abstract math
- $(I-A)p=f$
- compact operators

Announcements

- HW3
- Project Proposal

PDEs: Simple Ones First, More Complicated Ones Later

Laplace

$$\Delta u = 0$$

- ▶ Steady-state $\partial_t u = 0$ of wave propagation, heat conduction
- ▶ Electric potential u for applied voltage
- ▶ Minimal surfaces/“soap films”
- ▶ ∇u as velocity of incompressible flow

Helmholtz

$$\Delta u + k^2 u = 0$$

- ▶ Assume time-harmonic behavior $\tilde{u} = e^{\pm i\omega t} u(x)$ in time-domain wave equation:

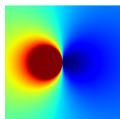
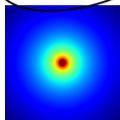
$$\partial_t^2 \tilde{u} = \Delta \tilde{u}$$

- ▶ Sign in \tilde{u} determines direction of wave: Incoming/outgoing if free-space problem
- ▶ *Applications:* Propagation of sound, electromagnetic waves

Fundamental Solutions

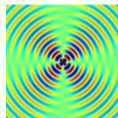
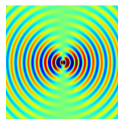
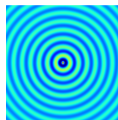
Laplace

$$-\Delta u = \delta$$



Helmholtz

$$\Delta u + k^2 u = \delta$$



aka. *Free space Green's Functions*

How do you assign a precise meaning to the statement with the δ -function?

$$\int \Delta u \varphi = \int \delta \varphi$$

Green's Functions

Why care about Green's functions?

$$\Delta u = f$$

$$\Delta G = \delta \quad \Rightarrow \quad \Delta (\overbrace{G * f}^u) = (\Delta G) * f = \delta * f = f$$

$$\partial_x (a * b) = (\partial_x a) * b \quad (G * f)(x) = \int_{\mathbb{R}^n} G(y) f(x-y) dy$$

What is a non-free-space Green's function? I.e. one for a specific domain?

$$\Delta u = 0 \quad u = g$$

on Ω on $\partial\Omega$

$G_d \leftarrow$ domain Green's function

$$u(x) = \int_{\partial\Omega} G_d(x-y) g(y) dS_y$$

Green's Functions (II)

Why not just use domain Green's functions?

They're unavailable.

What if we don't know a Green's function for our PDE... at all?

you can often still get away with
a "near match".

Fundamental Solutions

Laplace

$$G(x) = \begin{cases} \frac{1}{-2\pi} \log |x| & 2\text{D} \\ \frac{1}{4\pi} \frac{1}{|x|} & 3\text{D} \end{cases}$$

$$\frac{\partial}{\partial x} G(x)$$

Helmholtz

$$G(x) = \begin{cases} \frac{i}{4} H_0^1(k|x|) & 2\text{D} \\ \frac{1}{4\pi} \frac{e^{ik|x|}}{|x|} & 3\text{D} \end{cases}$$

$$\frac{\partial}{\partial x} G(x)$$

Layer Potentials (I)

$$\Gamma = \partial\Omega$$

$$\rightarrow (S_k\sigma)(x) := \int_{\Gamma} \underline{G}_k(x-y)\sigma(y)ds_y \quad \rightarrow \text{everywhere}$$

$$(S'_k\sigma)(x) := \underline{n \cdot \nabla_x} \text{PV} \int_{\Gamma} G_k(x-y)\sigma(y)ds_y \quad \rightarrow \Gamma$$

$$\rightarrow (D_k\sigma)(x) := \underline{\text{PV}} \int_{\Gamma} n \cdot \nabla_y G_k(x-y)\sigma(y)ds_y \quad \rightarrow \text{everywhere}$$

$$(D'_k\sigma)(x) := n \cdot \nabla_x \text{f.p.} \int_{\Gamma} n \cdot \nabla_y G_k(x-y)\sigma(y)ds_y \quad \rightarrow \Gamma$$

- ▶ G_k is the Helmholtz kernel ($k=0 \rightarrow$ Laplace)
- ▶ Operators map function σ on Γ to...
 - ▶ ...function on \mathbb{R}^n
 - ▶ ...function on Γ (in particular)

Layer Potentials (II)

- ▶ Alternate (“standard”) nomenclature:

Ours	Theirs
S	V
D	K
S'	K'
D'	T

- ▶ S'' (and higher) analogously
- ▶ Called *layer potentials*:
 - ▶ S is called the *single-layer potential*
 - ▶ D is called the *double-layer potential*
- ▶ (Show pictures using `pytential/examples/layerpot.py`, observe continuity properties.)

How does this actually solve a PDE?

Solve a (interior Laplace Dirichlet) BVP, $\partial\Omega = \Gamma$



$$\Delta u = 0 \quad \text{in } \Omega,$$

$$u|_{\Gamma} = f|_{\Gamma}.$$

$$S\sigma(x) = \int_{\Gamma} G(x,y)\sigma(y) d\mathcal{L}_y$$

\uparrow
 $\Delta G = \delta$

1. Pick representation:

$$u(x) := (S\sigma)(x)$$

2. Take (interior) limit onto Γ :

$$u|_{\Gamma} = S\sigma$$

$$\Delta(S\sigma)(x) =$$

$$= \int \underbrace{\Delta G(x,y)}_{x \in \Omega \rightarrow 0} \sigma(y) d\mathcal{L}_y$$

3. Enforce BC:

$$u|_{\Gamma} = f$$

4. Solve resulting linear system:

$$\int_{\Gamma} G(x,y)\sigma(y) d\mathcal{L}_y \quad \downarrow \quad S\sigma = f$$

$$= 0 \quad (I - K)$$

(quickly—using the methods we've developed: It is precisely of the form that suits our fast algorithms!)

5. Obtain PDE solution in Ω by evaluating representation

IE BVP Solve: Observations (I)

Observations:

- ▶ One can choose representations relatively freely. Only constraints:
 - ▶ Can I get to the solution with this representation?
I.e. is the solution I'm looking for represented?
 - ▶ Is the resulting integral equation solvable?

Q: How would we know?

IE BVP Solve: Observations (II)

- ▶ Some representations lead to better integral equations than others. The one above is actually terrible (both theoretically and practically). Fix above: Use $u(x) = D\sigma(x)$ instead of $u(x) = S\sigma(x)$.

Q: How do you tell a good representation from a bad one?

- ▶ Need to actually *evaluate* $S\sigma(x)$ or $D\sigma(x)$...

Q: How?

→ Need some theory

Outline

Introduction

Dense Matrices and Computation

Tools for Low-Rank Linear Algebra

Rank and Smoothness

Near and Far: Separating out High-Rank Interactions

Outlook: Building a Fast PDE Solver

Going Infinite: Integral Operators and Functional Analysis

Norms and Operators

Compactness

Integral Operators

Riesz and Fredholm

A Tiny Bit of Spectral Theory

Singular Integrals and Potential Theory

Boundary Value Problems

Back from Infinity: Discretization

Computing Integrals: Approaches to Quadrature

Going General: More PDEs

Norms

Definition

(Norm) A *norm* $\| \cdot \|$ maps an element of a *vector space* into $[0, \infty)$. It satisfies:

- ▶ $\|x\| = 0 \Leftrightarrow x = 0$
- ▶ $\|\lambda x\| = |\lambda| \|x\|$
- ▶ $\|x + y\| \leq \|x\| + \|y\|$ (triangle inequality)

Can create norm from *inner product*: $\|x\| = \sqrt{\langle x, x \rangle}$

Function Spaces

Name some function spaces with their norms.

$C(\Omega)$	f continuous, $\ f\ _\infty := \sup_{x \in \Omega} f(x) $
$C^k(\Omega)$	f k -times continuously differentiable
$C^{0,\alpha}(\Omega)$	$\ f\ _\alpha := \ f\ _\infty + \sup_{x \neq y} \frac{ f(x) - f(y) }{ x - y ^\alpha}$ ($\alpha \in (0, 1)$)
$C_L(\Omega)$	$ f(x) - f(y) \leq L\ x - y\ $
$L^p(\Omega)$	$\ f\ _p := \sqrt[p]{\int_D f(x) ^p dx} < \infty$
	L^2 special because?

Convergence

Name some ways in which a sequence can 'converge'.

Definition (Convergent sequence)

$x_n \rightarrow x \Leftrightarrow \|x_n - x\| \rightarrow 0$ "convergence in norm"

Definition (Cauchy sequence)

For all $\epsilon > 0$ there exists an n for which $\|x_\nu - x_\mu\| \leq \epsilon$ for $\mu, \nu \geq n$

(Convergence without known limit!)

Definition (Complete/"Banach" space)

Cauchy \Rightarrow Convergent

Q: Counterexample?

Operators

$$A(x+y) = Ax + Ay$$

X, Y : Banach spaces, $A : X \rightarrow Y$ linear operator



Definition (Operator norm)

$$\|A\| := \sup\{\|Ax\| : x \in X, \|x\| = 1\} \leftarrow$$

Theorem

$\|A\|$ bounded $\Leftrightarrow A$ continuous

Other facts?

- ▶ The set of bounded linear operators is itself a Banach space:
 $L(X, Y)$
- ▶ $\|Ax\| \leq \|A\|\|x\|$
- ▶ $\|BA\| \leq \|B\|\|A\|$

- ▶ What does 'linear' mean here?
- ▶ Is there a notion of 'continuous at x ' for linear operators? -

Operators: Examples

Which of these is bounded as an operator on functions on the real line?

▶ Multiplication by a scalar

▶ "Left shift"

▶ Fourier transform $\rightarrow L^1/L^2$

▶ Differentiation $\rightarrow C^1(\Omega), \|\cdot\|_{C^1}$

▶ Integration \rightarrow if Ω is bounded

▶ Integral operators (depends)

$$C(\mathbb{R}) \|\cdot\|_{\infty}$$

$$\|e^{i\alpha x}\|_{\infty} = 1$$
$$\|\partial_x e^{i\alpha x}\|_{\infty} = |\alpha|$$

Need to know spaces (norms really) to answer that!

Integral Equations: Zoology

Volterra

$$\int_a^x k(x,y)f(y)dy = g(x)$$

Fredholm

$$\int_G k(x,y)f(y)dy = g(x)$$

First kind

$$\int_G k(x,y)f(y)dy = g(x)$$

Second Kind

$$\mathcal{I}f(x) + \int_G k(x,y)f(y)dy = g(x)$$

Questions:

compact

compact

- ▶ First row: First or second kind?
- ▶ Second row: Volterra or Fredholm?
- ▶ Matrix (i.e. finite-dimensional) analogs?
- ▶ What can happen in 2D/3D?
- ▶ Factor allowable in front of the identity?

Volterra - triangular

▶ Why even talk about 'second-kind operators'? ←

- ▶ Throw a $+\delta(x-y)$ into the kernel, back to looking like first kind. So?
- ▶ Is the identity in $(I+K)$ crucial?

Connections to Complex Variables

Complex analysis is *full* of integral operators:

- ▶ Cauchy's integral formula:

$$f(a) = \frac{1}{2\pi i} \oint_{\gamma} \underbrace{\frac{1}{z-a}}_{\text{kernel}} \underbrace{f(z)}_{\text{function}} dz$$

- ▶ Cauchy's differentiation formula:

$$f^{(n)}(a) = \frac{n!}{2\pi i} \oint_{\gamma} \frac{1}{(z-a)^{n+1}} f(z) dz$$

Integral Operators: Boundedness (=Continuity)



$G \times G$

Theorem (Continuous kernel \Rightarrow bounded)

$G \subset \mathbb{R}^n$ closed, bounded ("compact"), $K \in C(\underline{G^2})$. Let

$$(A\phi)(x) := \int_G K(x, y)\phi(y)dy.$$

Then

$$\|A\|_\infty = \max_{x \in G} \int_G |K(x, y)| dy.$$

Show ' \leq '.

$$\begin{aligned} |A\phi(x)| &\leq \int |k(x, y)| |\phi(y)| dy \\ &\leq \int |k(x, y)/dy| \|\phi\|_\infty \\ &\leq \|A\|_\infty \|\phi\|_\infty \end{aligned}$$

Solving Integral Equations

Given

$$(A\phi)(x) := \int_G K(x, y)\phi(y)dy,$$

are we allowed to ask for a solution of

$$(\text{Id} + A)\phi = g?$$

Will see three attempts to answer that, in roughly historical order:

- ▶ Neumann
- ▶ Riesz
- ▶ Fredholm